

Large Deviations for Small Noise Stochastic Dynamical Systems

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based on joint works with

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Analysis of Stochastic Partial Differential Equations

Outline.

- Background.
- Small noise asymptotics.
- A variational representation for infinite dimensional BM.
- Applications to large deviations.
- Systems driven by fractional Brownian motions.
- Poisson random measures.
- Moderate deviations.

Large Deviation Principle.

Definition. Consider a sequence $\{X^\varepsilon\}_{\varepsilon>0}$ of \mathcal{E} valued r.v.s. \mathcal{E} - Polish.

- A function I from \mathcal{E} to $[0, \infty]$ is called a **rate function** on \mathcal{E} if for each $M < \infty$, $\{x \in \mathcal{E} : I(x) \leq M\}$ is compact.
- $\{X^\varepsilon\}$ is said to satisfy the **large deviation principle** on \mathcal{E} (as $\varepsilon \rightarrow 0$) with rate function I if:
 - For each closed subset F of \mathcal{E}

$$\limsup_{\varepsilon \rightarrow 0} \varepsilon \log \mathbb{P}(X^\varepsilon \in F) \leq -\inf_{x \in F} I(x).$$

- For each open subset G of \mathcal{E}

$$\liminf_{\varepsilon \rightarrow 0} \varepsilon \log \mathbb{P}(X^\varepsilon \in G) \geq -\inf_{x \in G} I(x).$$

Formally, for small ε :

$$\mathbb{P}(X^\varepsilon \in A) \approx \exp \left\{ -\frac{\inf_{x \in A} I(x)}{\varepsilon} \right\}, \quad A \in \mathcal{B}(\mathcal{E}).$$

Stochastic Control Connection (Fleming 1978)

Consider a small noise n -dimensional SDE:

$$dX^\varepsilon(t) = b(X^\varepsilon(t))dt + \sqrt{\varepsilon}\sigma(X^\varepsilon(t))dW(t), \quad X^\varepsilon(0) = x.$$

- b, σ suitable coefficients... W a f.d. BM.

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- b, σ suitable coefficients... W a f.d. BM.
- Let $G \subset \mathbb{R}^n$ be bounded open. Let $x \in G$ and $\tau^\varepsilon = \inf\{t : X^\varepsilon(t) \in \partial G\}$.
- Interested in $\lim_{\varepsilon \rightarrow 0} \varepsilon \log \mathbb{P}_x(X^\varepsilon(\tau^\varepsilon) \in N)$, where $N \subset \partial G$.

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- Formally, with Φ a nonnegative C^2 function, $\Phi(x) \approx M1_{N^c}(x)$, M a large scaler,

$$\lim_{\varepsilon \rightarrow 0} \varepsilon \log \mathbb{P}_x(X^\varepsilon(\tau^\varepsilon) \in N) \approx \lim_{\varepsilon \rightarrow 0} \varepsilon \log \mathbb{E}_x \left\{ e^{-\Phi(X^\varepsilon(\tau^\varepsilon))/\varepsilon} \right\}.$$

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- Then $g^\varepsilon(x) = \mathbb{E}_x \left\{ e^{-\Phi(X^\varepsilon(\tau^\varepsilon))/\varepsilon} \right\}$ solves

$$\begin{cases} \mathcal{L}^\varepsilon g^\varepsilon(x) = 0, & x \in G \\ g^\varepsilon(x) = e^{-\Phi(x)/\varepsilon}, & x \in \partial G \end{cases}$$

where $\mathcal{L}^\varepsilon g = \frac{\varepsilon}{2} \text{Tr}(\sigma D^2 g \sigma') + b \cdot \nabla g$.

Stochastic Control Connection (ctd.)

- **log transform:** Let $J^\varepsilon = -\varepsilon \log g^\varepsilon$. Then J^ε solves

$$\frac{\varepsilon}{2} \text{Tr}(\sigma D^2 J^\varepsilon \sigma') + H(x, \nabla J^\varepsilon) = 0$$

where

$$H(x, p) = \min_{v \in \mathbb{R}^n} [L(x, v) + p \cdot v], \quad x \in G, \quad p \in \mathbb{R}^n$$

and $L(x, v) = \frac{1}{2}(b(x) - v)'[\sigma(x)\sigma'(x)]^{-1}(b(x) - v)$.

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- J^ε can be characterized as the value function of the stochastic control problem:

$$J^\varepsilon(x) = \inf_{u \in \mathcal{A}} \mathbb{E}_x \left\{ \int_0^{\tau^\varepsilon} L(\tilde{X}^\varepsilon(t), u(t)) dt + \Phi(\tilde{X}^\varepsilon(\tau^\varepsilon)) \right\}$$

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$$d\tilde{X}^\varepsilon(t) = u(t)dt + \sqrt{\varepsilon}\sigma(X^\varepsilon(t))dW(t), \quad \tilde{X}^\varepsilon(0) = x$$

- One can argue $J^\varepsilon \rightarrow J$, where $J(x)$ is the value function of the deterministic control problem:

$$J(x) = \inf_{\phi, \theta} \int_0^\theta L(\phi(t), \dot{\phi}(t)) dt + \Phi(\phi(\theta)),$$

where inf is over all abs. cts. ϕ such that $\phi(0) = x$, and $\theta = \inf\{t : \phi(t) \in \partial G\}$.

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- **Later works:** Sheu (1985), Dupuis and Ellis(1997), Feng and Kurtz (2005).

Freidlin-Wentzell Asymptotics.

- Consider a small noise n -dimensional SDE:

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- Probabilities of 'deviations' $P(\sup_{0 \leq t \leq T} |X^\varepsilon(t) - \xi(t)| > c)$, studied by Freidlin-Wentzell by establishing a LDP.

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- – a starting point for studying asymptotics of exit times from domains, invariant measure asymptotics, metastability etc.
- ...also a basis for developing efficient importance sampling schemes.

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- ...also a basis for developing efficient importance sampling schemes.
- Here we revisit this problem – cover more general settings.
- infinite dimensional noise, Poisson random measures, fractional Brownian motions, moderate deviations problems.

LDP and Laplace Principle.

- LDP is equivalent to Laplace principle if the state space is Polish (Varadhan(1966), Bryc(1990)):
 - A collection of \mathcal{E} valued random variables $\{X^\epsilon\}$ is said to satisfy Laplace principle with rate function I , if for all $h \in C_b(\mathcal{E})$

$$\lim_{\epsilon \rightarrow 0} -\epsilon \log \mathbb{E} \left\{ \exp \left[-\frac{1}{\epsilon} h(X^\epsilon) \right] \right\} = \inf_{x \in \mathcal{E}} \{h(x) + I(x)\}.$$

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- From Donsker-Varadhan:

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- Goal is to show the **convergence of variational expressions**:

$$\inf_{Q \in \mathcal{P}(\mathcal{E})} \left[\int h(x) dQ(x) + R(Q \| P^\epsilon) \right] \xrightarrow{\epsilon \rightarrow 0} \inf_{x \in \mathcal{E}} \{h(x) + I(x)\}.$$

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- Instead of PDE characterizations – argue that for a family of ‘nice controls’ the (state, control, cost) sequence converges to the right limits

Variational Representations for Exponential Functionals of BM.

- Suppose $X^\epsilon = \mathcal{G}^\epsilon(\beta)$, \mathcal{G}^ϵ is a measurable map, β an infinite dimensional BM.
- First Step: Find convenient variational formulas for

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- Thus we seek variational representations for

$$-\log \mathbb{E}(\exp\{-f(\beta)\}),$$

f is bounded measurable.

Brownian Sheet.

- Let \mathcal{O} be a bounded open set in \mathbb{R}^d and $\{B(t, x), (t, x) \in [0, T] \times \mathcal{O}\}$ be a Brownian sheet.
I.e. it is a mean zero, continuous, Gaussian random field such that
 - $\text{Cov}(B(t, x), B(s, y)) = \text{Leb}(A_{t,x} \cap A_{s,y})$, where

$$A_{t,x} \doteq \{(s, y) : s \in [0, t], y \in \mathcal{O} \cap [0, x]\}.$$

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- B is a $(\mathbb{C}, \mathcal{B}(\mathbb{C}))$ valued r.v., where $\mathbb{C} = C([0, T] \times \overline{\mathcal{O}}; \mathbb{R})$ and $\mathcal{B}(\mathbb{C})$ the Borel sigma-field.
- Denote by μ the induced Wiener measure.
- Henceforth B is the canonical process on $(\mathbb{C}, \mathcal{B}(\mathbb{C}), \mu)$.

Representation for functionals of Brownian Sheet.

- Let $H \equiv L^2([0, T] \times \mathcal{O})$ and let

$$\mathcal{P}_2 \doteq \{u : u \text{ is } \mathcal{P} \otimes \mathcal{B}(\mathcal{O}) \text{ measurable and } u(\omega) \in H, \mu - a.s.\}.$$

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- For $\phi \in H$, define $\text{Int}(\phi) \in \mathbb{C}$ by

$$\text{Int}(\phi)(t, x) \doteq \int_{A_{t,x}} \phi(s, y) ds dy.$$

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- **Theorem.** [B., Dupuis (2000); B., Dupuis, Maroulas (2008).] Let $f : \mathbb{C} \rightarrow \mathbb{R}$ be a bounded measurable map. Let B be a Brownian sheet. Then

$$-\log \mathbb{E}(\exp\{-f(B)\}) = \inf_{u \in \mathcal{P}_2} \left\{ \mathbb{E} \left(\frac{1}{2} \|u\|_H^2 + f(B + \text{Int}(u)) \right) \right\}.$$

Remarks.

$$-\log \mathbb{E}(\exp\{-f(B)\}) = \inf_{u \in \mathcal{P}_2} \left\{ \mathbb{E}^\mu \left(\frac{1}{2} \|u\|_H^2 + f(B + \text{Int}(u)) \right) \right\}.$$

- From the Donsker-Varadhan formula:

$$-\log \mathbb{E}(\exp\{-f(B)\}) = \inf_{Q \in \mathcal{P}(\mathbb{C})} \mathbb{E}^Q [f(B) + R(Q \parallel \mu)].$$

From this one can deduce:

$$-\log \mathbb{E}(\exp\{-f(B)\}) \leq \inf_{\{\text{nice } u \in \mathcal{P}_2\}} \left\{ \mathbb{E}^{Q_u} \left(\frac{1}{2} \|u\|_H^2 + f(B^u + \text{Int}(u)) \right) \right\}.$$

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- Zhang (2009): Setting of an abstract Wiener space.

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- Üstünel(2009): Connections with Monge-Kantorovitch problem.
- Obtaining optimal controls:
 - Üstünel(2009) – in terms of Clark-Ocone formula.
 - Chen-Xiong (2010) – through solutions of BSDEs.

A LDP for functionals of BS.

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- Typical example of X^ε : **Solution of a small noise SPDE.**
- Then

$$-\varepsilon \log \mathbb{E}\left\{\exp\left[-\frac{1}{\varepsilon}h(X^\varepsilon)\right]\right\} = -\varepsilon \log \mathbb{E}\left\{\exp\left[-\frac{1}{\varepsilon}h(\mathcal{G}^\varepsilon(\sqrt{\varepsilon}B))\right]\right\}.$$

LDP for $X^\varepsilon \doteq \mathcal{G}^\varepsilon(\sqrt{\varepsilon}B)$.

- Let

$$S^M \doteq \{\phi \in H : \|\phi\|_H^2 \leq M\}.$$

- S^M is compact with the weak topology.
- Define

$$\mathcal{P}_2^M \doteq \{u : u \in \mathcal{P}_2 : u(\omega) \in S^M, \mu - a.s.\}.$$

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- **Assumption.** There exists a measurable map $\mathcal{G}^0 : \mathbb{C} \rightarrow \mathcal{E}$ such that:
For every $M < \infty$:
 - Whenever $\{u_n\} \subset \mathcal{P}_2^M$ is such that $u_n \Rightarrow u$ (as S^M -valued random elements), and $\varepsilon_n \in [0, 1)$ is such that $\varepsilon_n \rightarrow 0$, we have

$$\mathcal{G}^{\varepsilon_n}(\sqrt{\varepsilon_n}B + \text{Int}(u_n)) \Rightarrow \mathcal{G}^0(\text{Int}(u)).$$

- **Theorem.** [B., Dupuis, Maroulas (2008).] Suppose Assumption holds. Then, the family $\{X^\varepsilon\}$ satisfies LDP on \mathcal{E} , with rate function

$$I(f) \doteq \inf_{\{u \in H : f = \mathcal{G}^0(\text{Int}(u))\}} \left\{ \frac{1}{2} \|u\|_H^2 \right\}.$$

Sketch of Proof.

- Suffices to show that **Laplace principle** holds: For all $h \in C_b(\mathcal{E})$

$$\lim_{\epsilon \rightarrow 0} -\epsilon \log \mathbb{E} \left\{ \exp \left[-\frac{1}{\epsilon} h(X^\epsilon) \right] \right\} = \inf_{x \in \mathcal{E}} \{h(x) + I(x)\}.$$

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- Recall $X^\epsilon \doteq \mathcal{G}^\epsilon(\sqrt{\epsilon}B)$. Applying reprn. with $f = \frac{1}{\epsilon} h \circ \mathcal{G}^\epsilon(\sqrt{\epsilon}\cdot)$ we have

$$-\epsilon \log \mathbb{E} \left\{ \exp \left[-\frac{1}{\epsilon} h(X^\epsilon) \right] \right\} = \inf_u \mathbb{E} \left(\frac{1}{2} \|u\|_H^2 + h(X^{\epsilon,u}) \right),$$

where $X^{\epsilon,u} = \mathcal{G}^\epsilon(\sqrt{\epsilon}B + \text{Int}(u))$.

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Applications.

- Hilbert Space Valued Diffusions. Unique solvability studied in Leha and Ritter (1984). [Small noise LDP in B.-Dupuis\(2000\)](#).
- Stochastic reaction diffusion equations. Prior works on LDP: Freidlin(1988), Zabczyk(1988), Sowers(1992), Kallianpur and Xiong(1995). These papers assume diffusion coefficient is bounded, “cone condition” on domain... conditions needed for tail probability estimates on certain stochastic convolutions in Holder norms – Garsia’s Theorem.
[Conditions relaxed in B.-Dupuis-Maroulas\(2008\)](#).
- [Stochastic flows of diffeomorphisms. B.-Dupuis-Maroulas\(2009\)](#). Prior works include Millet, Nualart and Sanz-Sole(1992), Ben Arous and Castell(1995)—these concern finite dimensional flows.

– asymptotic relation, **in terms of the rate function**, between (small noise) Bayesian solution of an image matching problem with the solution of a deterministic variational problem.

Advantages of the Approach.

- No approximations or discretizations.
- Exponential prob. estimates are completely bypassed.
- Uniqueness results for HJ equations not needed.
- Proofs of LDP reduce to demonstrating basic qualitative properties of certain perturbations of the original system (eg. existence, uniqueness, stability under L^2 -bounded perturbations).

Other Applications.

- **Fluid dynamics models.**
 - 2D Navier-Stokes equation with multiplicative noise (Sritharan and Sundar (2006)), stochastic tamed 3D Navier-Stokes equations (Rockner, Zhang, Zhang (2010)), Boussinesq equations under random influences (Duan and Millet (2009)), inviscid shell models (Bessaih and Millet (2009)), 2D Navier Stokes equations with a free boundary condition (Bessaih and Millet (2010)), stochastic shell model of turbulence (Manna, Sritharan and Sundar (2010)), stochastic 2D hydrodynamical type systems (Chueshov and Millet (2010)), stochastic derivative Ginzburg-Landau equation with multiplicative noise (Yang and Hou (2008)).
- **Less Regular Coefficients.**
 - Homeomorphism flows of non-Lipschitz multi-dimensional SDEs (Ren and Zhang (2005)), degenerate SDEs with Sobolev coefficients (Zhang (2010)), multivalued stochastic differential equations (Ren, Xu and Zhang (2010)), stochastic variational inequalities (Bo and Jiang (2011)).
- **Other examples.**
 - Stochastic partial differential equations under fast dynamical boundary conditions (Wang and Duan (2009)), SPDEs with reflection (Xu and Zhang (2009)), 3D stochastic wave equation (Ortiz-Lopez and Sanz-Sole (2010)), stochastic Volterra equations in Banach spaces (Zhang (2010)).

Variational Representation for PRM.

- Let \mathbb{X} be a complete separable, locally compact metric space.
- \mathbb{M} be the space of all locally finite measures on $\mathbb{X}_T = [0, T] \times \mathbb{X}$.
- The space is endowed with the weakest topology such that $\mathbb{M} \ni \lambda \mapsto \int f d\lambda$ is continuous for all $f \in C_c(\mathbb{X}_T)$.

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- N^θ can be represented as

$$N^\theta((0, t] \times U) = \int_{(0, t] \times U \times (0, \infty)} \mathbf{1}_{[0, \theta]}(r) \bar{N}(ds dx dr),$$

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- Let $\bar{\mathcal{A}} = \{\varphi : [0, T] \times \mathbb{X} \times \Omega \rightarrow [0, \infty), \text{ predictable, measurable}\}$. For $\varphi \in \bar{\mathcal{A}}$, N^φ defined similarly:

$$N^\varphi((0, t] \times U) = \int_{(0,t] \times U \times (0,\infty)} 1_{[0,\varphi(s,x,\omega)]}(r) \bar{N}(ds dx dr),$$

Variational Representation for PRM (ctd.).

- Let $\ell : [0, \infty) \rightarrow (0, \infty)$

$$\ell(r) = r \log r - r + 1, \quad r \in [0, \infty).$$

For $\varphi \in \bar{\mathcal{A}}$, define

$$L_T(\varphi)(\omega) = \int_{\mathbb{X}_T} \ell(\varphi(t, x, \omega)) \nu_T(dt dx), \quad \omega \in \bar{\mathbb{M}}.$$

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- **Theorem** [B., Dupuis and Maroulas(2010).] Let f be a bounded measurable map from $\mathbb{M} \rightarrow \mathbb{R}$. Then, for $\theta > 0$

$$-\log \mathbb{E}(e^{-f(N^\theta)}) = \inf_{\varphi \in \bar{\mathcal{A}}} \mathbb{E} [\theta L_T(\varphi) + f(N^{\theta\varphi})].$$

- A different repn obtained in Zhang(2009) - not suitable for large deviation applications.

Application to Large Deviations.

- $\beta \equiv (\beta_i)_{i=1}^\infty$ is an i.i.d. family of standard Brownian motions.
- $N^{\varepsilon^{-1}}$ is a PRM with intensity measure $\varepsilon^{-1}\nu_T$.
- Let $\mathbb{V} = C([0, \infty) : \mathbb{R}^\infty) \times \mathbb{M}$. Let $\mathcal{G}^\varepsilon : \mathbb{V} \rightarrow \mathbb{U}$, where \mathbb{U} is a Polish space, be a sequence of measurable maps.
- Interested in large deviation principle for

$$Z^\varepsilon = \mathcal{G}^\varepsilon(\sqrt{\varepsilon}\beta, \varepsilon N^{\varepsilon^{-1}}).$$

- For $M \in \mathbb{N}$, let

$$\tilde{S}^M = \left\{ \phi \in L^2([0, T] : \ell_2) : \tilde{L}_T(\phi) \equiv \int_0^T \|\phi\|_2^2 \leq M \right\}.$$

$$\bar{S}^M = \{ \psi : [0, T] \times \mathbb{X} \rightarrow (0, \infty) : L_T(\psi) \leq M \}.$$

- Identify a function $\psi \in \bar{S}^M$ with the measure $\nu_T^\psi \in \mathbb{M}$, through

$$\nu_T^\psi(A) = \int_A \psi(s, x) \nu_T(dsdx).$$

- With 'weak' topology $S^M = \bar{S}^M \times \tilde{S}^M$ is a compact metric space. Let \mathcal{U}^M be the space of S^M valued controls that are 'non-anticipative'.

Application to Large Deviations.

$$Z^\varepsilon = \mathcal{G}^\varepsilon(\sqrt{\varepsilon}\beta, \varepsilon N^{\varepsilon^{-1}}).$$

- **Main Condition.** There exists a measurable map $\mathcal{G}^0 : \mathbb{V} \rightarrow \mathbb{U}$ such that:
For every $M < \infty$:
 - Whenever $\{u_n = (\psi_n, \varphi_n)\} \subset \mathcal{U}^M$ is such that $u_n \Rightarrow u$ (as S^M -valued random elements), and $\varepsilon_n \in [0, 1)$ is such that $\varepsilon_n \rightarrow 0$, we have

$$\mathcal{G}^{\varepsilon_n} \left(\sqrt{\varepsilon_n}\beta + \int_0^\cdot \psi_n(s) ds, \varepsilon_n N^{\varepsilon_n^{-1}\varphi_n} \right) \Rightarrow \mathcal{G}^0 \left(\int_0^\cdot \psi(s) ds, \nu_T^\varphi \right).$$

- Let $\mathbb{S} = \cup_{M \in \mathbb{N}} S^M$. For $\phi \in \mathbb{U}$, define

$$\mathbb{S}_\phi = \left\{ (f, g) \in \mathbb{S} : \phi = \mathcal{G}^0 \left(\int_0^\cdot f(s) ds, g \right) \right\}.$$

Let I be the rate function defined as

$$I(\phi) = \inf_{q=(f,g) \in \mathbb{S}_\phi} \left\{ \frac{1}{2} \|f\|_H^2 + L_T(g) \right\}.$$

- **Theorem** [B., Dupuis and Maroulas(2010)] Under the condition above $\{Z^\varepsilon\}_{\varepsilon>0}$ satisfies a LDP with rate function I .

Applications.

- Advection-Diffusion Equation with Poissonian Sources (B., Chen, Dupuis(2013))
- Large Deviations for Stochastic Averaging Problems for jump-diffusions (B., Chen Dupuis(201?)).

Fractional Brownian Motion.

- Let $\{B_t^H, t \in [0, 1]\}$ be a d -dimensional fBM with Hurst parameter $H \in (0, 1)$ on (Ω, \mathcal{F}, P) .

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- This kernel describes a Hilbert space \mathcal{H} as the collection of all $h : [0, 1] \rightarrow \mathbb{R}^d$ such that

$$h(t) = (K_H \dot{h})(t) = \int_0^1 K_H(t, s) \dot{h}(s) ds, \quad t \in [0, 1],$$

for some $\dot{h} \in L^2([0, 1] : \mathbb{R}^d)$. Inner product on \mathcal{H} :

$$\langle h, g \rangle_{\mathcal{H}} = \langle K_H \dot{h}, K_H \dot{g} \rangle_{\mathcal{H}} = \langle \dot{h}, \dot{g} \rangle_{L^2}.$$

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- Let $\{B_t^H, t \in [0, 1]\}$ be a d -dimensional fBM with Hurst parameter $H \in (0, 1)$ on (Ω, \mathcal{F}, P) .
- B^H has a representation:

$$B_t^H = \int_0^1 K_H(t, s) dB_s,$$

where $K_H : [0, 1] \times [0, 1] \rightarrow \mathbb{R}$ and B is a standard d -dimensional BM.

- This kernel describes a Hilbert space \mathcal{H} as the collection of all $h : [0, 1] \rightarrow \mathbb{R}^d$ such that

$$h(t) = (K_H \dot{h})(t) = \int_0^1 K_H(t, s) \dot{h}(s) ds, \quad t \in [0, 1],$$

for some $\dot{h} \in L^2([0, 1] : \mathbb{R}^d)$. Inner product on \mathcal{H} :

$$\langle h, g \rangle_{\mathcal{H}} = \langle K_H \dot{h}, K_H \dot{g} \rangle_{\mathcal{H}} = \langle \dot{h}, \dot{g} \rangle_{L^2}.$$

- Let $\mathcal{F}_t^H = \overline{\sigma\{B_s^H : s \leq t\}}$ and let \mathcal{A} be the family of all \mathcal{F}_t^H adapted \mathcal{H} valued random variables.

Representation for fBM:

- Let f be a real bounded measurable function on $C([0, 1] : \mathbb{R}^d)$. Then

$$-\log E \left(e^{-f(B^H)} \right) = \inf_{v \in \mathcal{A}} E \left(f(B^H + v) + \frac{1}{2} \|v\|_{\mathcal{H}}^2 \right).$$

SDE driven by fBM ($H > 1/2$).

- Consider the SDE

$$X_t^\varepsilon = x_0 + \int_0^t b(s, X_s^\varepsilon) ds + \sqrt{\varepsilon} \int_0^t \sigma(s, X_s^\varepsilon) dB_s^H, \quad t \in [0, 1].$$

- For some $L > 0$

$$|b(t, x) - b(t, y)| \leq L|x - y|, \quad |b(t, x)| \leq L(1 + |x|) \quad \forall x, y \in \mathbb{R}^d, \quad \forall t \in [0, 1].$$

- $\sigma(t, x) : [0, 1] \times \mathbb{R}^m \rightarrow \mathbb{R}^{m \times d}$ is differentiable in x , and for some $M > 0$, $1 - H < \lambda \leq 1$, $\frac{1}{H} - 1 < \gamma \leq 1$ and $\forall N > 0$ there exists $M_N > 0$ s.t.

$$|\sigma(t, x) - \sigma(t, y)| \leq M|x - y|, \quad \forall x \in \mathbb{R}^m, \quad \forall t \in [0, 1],$$

$$|\partial_{x_i} \sigma(t, x) - \partial_{y_i} \sigma(t, y)| \leq M_N |x - y|^\gamma, \quad \forall |x|, |y| \leq N, \quad \forall t \in [0, 1],$$

$$|\sigma(t, x) - \sigma(s, x)| + |\partial_{x_i} \sigma(t, x) - \partial_{x_i} \sigma(s, x)| \leq M|t - s|^\lambda, \quad \forall x \in \mathbb{R}^m, \quad \forall t, s \in [0, 1],$$

for each $i = 1, \dots, m$.

- There exist $0 \leq \rho \leq 2 - \frac{1}{H}$ and $K > 0$ such that

$$|\sigma(t, x)| \leq K(1 + |x|^\rho), \quad \forall x \in \mathbb{R}^m, \quad \forall t \in [0, 1].$$

- Existence and uniqueness of solutions shown in Nualart and Rascanu(2002).

SDE driven by fBM (ctd.)

- **Theorem** (B., Pipiras and Song(201?).) Under the above conditions, $\{X^\varepsilon\}_{\varepsilon>0}$ satisfies a LDP in $C^\alpha([0, 1]; \mathbb{R}^m)$ for any $\alpha \in (1 - H, \min\{\frac{1}{2}, \lambda, \frac{\gamma}{1+\gamma}\})$, with the rate function

$$I(f) = \inf_v \left\{ \frac{1}{2} \|v\|_{\mathcal{H}}^2 \right\}$$

where the infimum is taken over

$$\{v \in \mathcal{H} : f_t = x_0 + \int_0^t b(s, f_s) ds + \int_0^t \sigma(s, f_s) dv_s\}.$$

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$$\text{LDP: } P(|S_n| > nc) \approx \exp \left\{ -n \inf_{|y| \geq c} I(y) \right\},$$

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- **Definition.** A collection of random variables $\{X^\varepsilon\}$ of \mathcal{E} valued random variables satisfies a LDP on \mathcal{E} with speed $b(\varepsilon)^{-1}$ and rate function I of for all $h \in C_b(\mathcal{E})$.

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- The example says
 - $\frac{S_n}{n}$ satisfies a LDP with speed n and rate function I .
 - $\frac{S_n}{n^{1/2} a_n}$ satisfies a LDP with speed a_n^2 and rate function I^0 .

Moderate Deviations for SDEs.

- Consider the SDE:

$$X^\varepsilon(t) = x_0 + \int_0^t b(X^\varepsilon(s))ds + \sqrt{\varepsilon} \int_0^t \sigma(X^\varepsilon(s))dW(s) + \varepsilon \int_{\mathbb{X} \times [0,t]} G(X^\varepsilon(s-), y) N^{\varepsilon^{-1}}(dsdy).$$

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$$|G(x, y) - G(x', y)| \leq L_G(y)|x - x'|, \quad x, x' \in \mathbb{R}, \quad y \in \mathbb{X},$$

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- Let $a(\varepsilon) \rightarrow 0$ and $b(\varepsilon) = \varepsilon/a^2(\varepsilon) \rightarrow 0$, Consider $Y^\varepsilon = \frac{1}{a(\varepsilon)}(X^\varepsilon - X^0)$.

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- **Theorem.** (B., Dupuis and Ganguly (2017?)). In addition to the above conditions on b, σ and G , suppose that

- L_G and M_G are in

$$\left\{ h : \mathbb{X} \rightarrow \mathbb{R} : \exists \delta_1 > 0, \text{ s.t. } \forall \Gamma \text{ with } \nu(\Gamma) < \infty \int_{\Gamma} \exp(\delta_1 h^2(y)) \nu(dy) < \infty \right\}.$$

- The maps $x \mapsto b(x)$ and, for every $y \in \mathbb{X}$, $x \mapsto G(x, y)$ are differentiable. For some $L_{Db} \in (0, \infty)$ and $L_{DG} \in L_2(\nu)$

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- For every $\rho > 0$,

$$\sup_{|x| \leq \rho} \int_{\mathbb{X}} |D_x G(x, y)| \nu(dy) < \infty.$$

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$$I(\eta) = \inf_{\psi, u} \left\{ \frac{1}{2} \|\psi\|_2^2 + \frac{1}{2} |u|^2 \right\}$$

where the infimum is taken over all $\psi \in L^2(\nu_T)$, $u \in L^2(\mathbb{R}^d)$ such that

$$\begin{aligned} \eta(t) &= \int_0^t [Db(X^0(s))] (\eta(s)) ds + \int_{\mathbb{X} \times [0, t]} [D_x G(X^0(s), y)] (\eta(s)) \nu(dy) ds \\ &+ \int_{\mathbb{X} \times [0, t]} \psi(y, s) G(X^0(s), y) \nu(dy) ds + \int_{[0, t]} \sigma(X^0(s)) u(s) ds. \end{aligned}$$

Moderate Deviations for SDEs.

In other words the rate function is the same as that for LDP (with speed ε) for a Gaussian process U^ε that solves

$$U^\varepsilon(t) = \int_0^t A(s)U^\varepsilon(s)ds + \sqrt{\varepsilon} \int_0^t B_1(s)dW_1(s) + \sqrt{\varepsilon} \int_0^t B_2(s)dW_2(s)$$

- W_1, W_2 are independent d -dimensional Brownian motions.
- $A(s) = DB(X^0(s)) + \int_{\mathbb{X}} D_x G(x, y)\nu(dy)$.
- $B_1(s) = \|G(X^0(s), \cdot)\|_2 I_{d \times d}$.
- $B_2(s) = \sigma(X^0(s))$.