

# Hitting probabilities for systems of stochastic partial differential equations: an overview

Robert C. Dalang

Ecole Polytechnique Fédérale de Lausanne

Based on joint works with:

Davar Khoshnevisan, Eulalia Nualart  
Marta Sanz-Solé  
Carl Mueller, Yimin Xiao

- Introduction to the problem of hitting probabilities
- Benchmark results in the Gaussian case
- Conditions for non-Gaussian random fields
- Our results for systems of stochastic heat and wave equations
- Handling the critical dimension?

## Fundamental problem in probabilistic potential theory

Let  $U = (U(x), x \in \mathbb{R}^k)$  be an  $\mathbb{R}^d$ -valued continuous stochastic process.

Fix  $I \subset \mathbb{R}^k$ , compact with positive Lebesgue measure.

The **range of  $U$**  over  $I$  is the random compact set

$$U(I) = \{U(x), x \in I\}.$$

**Question.** For  $A \subset \mathbb{R}^d$ , what are bounds on

$$P\{U(I) \cap A \neq \emptyset\}?$$

**Hitting points.** Fix  $z \in \mathbb{R}^d$ . Is  $P\{\exists x \in I : U(x) = z\} > 0$ ?

Which sets  $A \subset \mathbb{R}^d$  are **polar**:  $P\{U(I) \cap A \neq \emptyset\} = 0$ ?

What is the Hausdorff dimension of the **range** of  $U$ ?

What is the Hausdorff dimension of **level sets** of  $U$ ?

## Fundamental problem in probabilistic potential theory

Let  $U = (U(x), x \in \mathbb{R}^k)$  be an  $\mathbb{R}^d$ -valued continuous stochastic process.

Fix  $I \subset \mathbb{R}^k$ , compact with positive Lebesgue measure.

The **range of  $U$**  over  $I$  is the random compact set

$$U(I) = \{U(x), x \in I\}.$$

**Question.** For  $A \subset \mathbb{R}^d$ , what are bounds on

$$P\{U(I) \cap A \neq \emptyset\}?$$

**Hitting points.** Fix  $z \in \mathbb{R}^d$ . Is  $P\{\exists x \in I : U(x) = z\} > 0$ ?

Which sets  $A \subset \mathbb{R}^d$  are **polar**:  $P\{U(I) \cap A \neq \emptyset\} = 0$ ?

What is the Hausdorff dimension of the **range** of  $U$ ?

What is the Hausdorff dimension of **level sets** of  $U$ ?

# Fundamental problem in probabilistic potential theory

Let  $U = (U(x), x \in \mathbb{R}^k)$  be an  $\mathbb{R}^d$ -valued continuous stochastic process.

Fix  $I \subset \mathbb{R}^k$ , compact with positive Lebesgue measure.

The **range of  $U$**  over  $I$  is the random compact set

$$U(I) = \{U(x), x \in I\}.$$

**Question.** For  $A \subset \mathbb{R}^d$ , what are bounds on

$$P\{U(I) \cap A \neq \emptyset\}?$$

**Hitting points.** Fix  $z \in \mathbb{R}^d$ . Is  $P\{\exists x \in I : U(x) = z\} > 0$ ?

Which sets  $A \subset \mathbb{R}^d$  are **polar**:  $P\{U(I) \cap A \neq \emptyset\} = 0$ ?

What is the Hausdorff dimension of the **range** of  $U$ ?

What is the Hausdorff dimension of **level sets** of  $U$ ?

## First example: the Brownian sheet

Let  $(W(x), x \in \mathbb{R}_+^k)$  denote an  $k$ -parameter  $\mathbb{R}^d$ -valued **Brownian sheet**, that is, a centered continuous Gaussian random field

$$W(x) = (W_1(x), \dots, W_d(x))$$

with covariance

$$E[W_i(x)W_j(y)] = \prod_{\ell=1}^k \min(x_\ell, y_\ell) \delta_{i,j}, \quad i, j \in \{1, \dots, d\},$$

where  $x = (x_1, \dots, x_k)$  and  $y = (y_1, \dots, y_k)$ .

The case  $k = 1$ : Brownian motion  $B = (B(t), t \in \mathbb{R}_+)$ .

The case  $k > 1$ : multi-parameter extension of Brownian motion.

*A few references:* Orey & Pruitt (1973), R. Adler (1978), W. Kendall (1980), J.B. Walsh (1986), D. & Walsh (1992), Khoshnevisan & Shi (1999)  
D. Khoshnevisan, *Multiparameter processes*, Springer (2002).

## First example: the Brownian sheet

Let  $(W(x), x \in \mathbb{R}_+^k)$  denote an  $k$ -parameter  $\mathbb{R}^d$ -valued **Brownian sheet**, that is, a centered continuous Gaussian random field

$$W(x) = (W_1(x), \dots, W_d(x))$$

with covariance

$$E[W_i(x)W_j(y)] = \prod_{\ell=1}^k \min(x_\ell, y_\ell) \delta_{i,j}, \quad i, j \in \{1, \dots, d\},$$

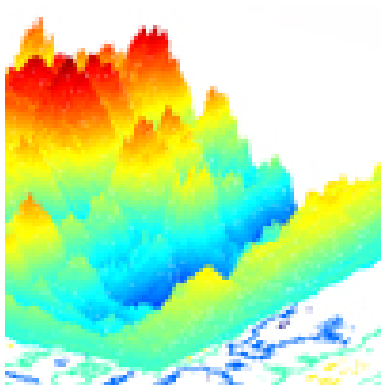
where  $x = (x_1, \dots, x_k)$  and  $y = (y_1, \dots, y_k)$ .

The case  $k = 1$ : Brownian motion  $B = (B(t), t \in \mathbb{R}_+)$ .

The case  $k > 1$ : multi-parameter extension of Brownian motion.

**A few references:** Orey & Pruitt (1973), R. Adler (1978), W. Kendall (1980), J.B. Walsh (1986), D. & Walsh (1992), Khoshnevisan & Shi (1999)

D. Khoshnevisan, *Multiparameter processes*, Springer (2002).

A sample path of the Brownian sheet  $N = 2$ ,  $d = 1$ 



## Hitting probabilities for the Brownian sheet

Let  $(W(x), x \in \mathbb{R}_+^k)$  denote a  $k$ -parameter  $\mathbb{R}^d$ -valued Brownian sheet.

**Theorem 1 (Khoshnevisan and Shi, 1999)**

Fix  $M > 0$  and  $0 < a_\ell < b_\ell < \infty$  ( $\ell = 1, \dots, k$ ). Let

$$I = [a_1, b_1] \times \cdots \times [a_k, b_k] \quad (\subset \mathbb{R}^k).$$

There exists  $0 < C < \infty$  such that for all compact sets  $A \subset B(0, M)$  ( $\subset \mathbb{R}^d$ ),

$$\frac{1}{C} \text{Cap}_{d-2k}(A) \leq P\{W(I) \cap A \neq \emptyset\} \leq C \text{Cap}_{d-2k}(A).$$

(see also results of F. Hirsch and S. Song (1991, 1995)).

## Measuring the size of sets: capacity

**Capacity.**  $\text{Cap}_\beta(A)$  denotes the **Bessel-Riesz capacity** of  $A$ :

$$\text{Cap}_\beta(A) = \frac{1}{\inf_{\mu \in \mathcal{P}(A)} \mathcal{E}_\beta(\mu)},$$

$$\mathcal{E}_\beta(\mu) = \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} k_\beta(x-y) \mu(dx) \mu(dy)$$

and

$$k_\beta(x) = \begin{cases} \|x\|^{-\beta} & \text{if } 0 < \beta < d, \\ \ln\left(\frac{1}{\|x\|}\right) & \text{if } \beta = 0, \\ 1 & \text{if } \beta < 0. \end{cases}$$

**Examples.** If  $A = \{z\}$ , then:

$$\text{Cap}_\beta(\{z\}) = \begin{cases} 1 & \text{if } \beta < 0, \\ 0 & \text{if } \beta \geq 0. \end{cases}$$

If  $A$  is a subspace of  $\mathbb{R}^d$  with dimension  $\ell \in \{1, \dots, d-1\}$ , then:

$$\text{Cap}_\beta(A) \begin{cases} > 0 & \text{if } \beta < \ell, \\ = 0 & \text{if } \beta \geq \ell. \end{cases}$$

## Measuring the size of sets: capacity

**Capacity.**  $\text{Cap}_\beta(A)$  denotes the **Bessel-Riesz capacity** of  $A$ :

$$\text{Cap}_\beta(A) = \frac{1}{\inf_{\mu \in \mathcal{P}(A)} \mathcal{E}_\beta(\mu)},$$

$$\mathcal{E}_\beta(\mu) = \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} k_\beta(x-y) \mu(dx) \mu(dy)$$

and

$$k_\beta(x) = \begin{cases} \|x\|^{-\beta} & \text{if } 0 < \beta < d, \\ \ln\left(\frac{1}{\|x\|}\right) & \text{if } \beta = 0, \\ 1 & \text{if } \beta < 0. \end{cases}$$

**Examples.** If  $A = \{z\}$ , then:

$$\text{Cap}_\beta(\{z\}) = \begin{cases} 1 & \text{if } \beta < 0, \\ 0 & \text{if } \beta \geq 0. \end{cases}$$

If  $A$  is a subspace of  $\mathbb{R}^d$  with dimension  $\ell \in \{1, \dots, d-1\}$ , then:

$$\text{Cap}_\beta(A) \begin{cases} > 0 & \text{if } \beta < \ell, \\ = 0 & \text{if } \beta \geq \ell. \end{cases}$$

## Measuring the size of sets: capacity

**Capacity.**  $\text{Cap}_\beta(A)$  denotes the **Bessel-Riesz capacity** of  $A$ :

$$\text{Cap}_\beta(A) = \frac{1}{\inf_{\mu \in \mathcal{P}(A)} \mathcal{E}_\beta(\mu)},$$

$$\mathcal{E}_\beta(\mu) = \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} k_\beta(x-y) \mu(dx) \mu(dy)$$

and

$$k_\beta(x) = \begin{cases} \|x\|^{-\beta} & \text{if } 0 < \beta < d, \\ \ln\left(\frac{1}{\|x\|}\right) & \text{if } \beta = 0, \\ 1 & \text{if } \beta < 0. \end{cases}$$

**Examples.** If  $A = \{z\}$ , then:

$$\text{Cap}_\beta(\{z\}) = \begin{cases} 1 & \text{if } \beta < 0, \\ 0 & \text{if } \beta \geq 0. \end{cases}$$

If  $A$  is a subspace of  $\mathbb{R}^d$  with dimension  $\ell \in \{1, \dots, d-1\}$ , then:

$$\text{Cap}_\beta(A) \begin{cases} > 0 & \text{if } \beta < \ell, \\ = 0 & \text{if } \beta \geq \ell. \end{cases}$$

## Another measure of the size of sets: Hausdorff measure

For  $\beta \geq 0$ , the  $\beta$ -dimensional **Hausdorff measure** of  $A$  is defined by

$$\mathcal{H}_\beta(A) = \lim_{\epsilon \rightarrow 0^+} \inf \left\{ \sum_{i=1}^{\infty} (2r_i)^\beta : A \subseteq \bigcup_{i=1}^{\infty} B(x_i, r_i), \sup_{i \geq 1} r_i \leq \epsilon \right\}.$$

When  $\beta < 0$ , we define  $\mathcal{H}_\beta(A)$  to be infinite.

**Note.** For  $\beta_1 > \beta_2 > 0$ ,

$$\text{Cap}_{\beta_1}(A) > 0 \Rightarrow \mathcal{H}_{\beta_1}(A) > 0 \Rightarrow \text{Cap}_{\beta_2}(A) > 0.$$

**Example.**  $A = \{z\}$

$$\mathcal{H}_\beta(\{z\}) = \begin{cases} \infty & \text{if } \beta < 0 \\ 1 & \text{if } \beta = 0 \\ 0 & \text{if } \beta > 0. \end{cases}$$

**Remark.** For  $\beta = 0$ ,

$$\text{Cap}_0(\{z\}) = 0 < \mathcal{H}_0(\{z\}) = 1.$$

## Another measure of the size of sets: Hausdorff measure

For  $\beta \geq 0$ , the  $\beta$ -dimensional **Hausdorff measure** of  $A$  is defined by

$$\mathcal{H}_\beta(A) = \lim_{\epsilon \rightarrow 0^+} \inf \left\{ \sum_{i=1}^{\infty} (2r_i)^\beta : A \subseteq \bigcup_{i=1}^{\infty} B(x_i, r_i), \sup_{i \geq 1} r_i \leq \epsilon \right\}.$$

When  $\beta < 0$ , we define  $\mathcal{H}_\beta(A)$  to be infinite.

**Note.** For  $\beta_1 > \beta_2 > 0$ ,

$$\text{Cap}_{\beta_1}(A) > 0 \Rightarrow \mathcal{H}_{\beta_1}(A) > 0 \Rightarrow \text{Cap}_{\beta_2}(A) > 0.$$

**Example.**  $A = \{z\}$

$$\mathcal{H}_\beta(\{z\}) = \begin{cases} \infty & \text{if } \beta < 0 \\ 1 & \text{if } \beta = 0 \\ 0 & \text{if } \beta > 0. \end{cases}$$

**Remark.** For  $\beta = 0$ ,

$$\text{Cap}_0(\{z\}) = 0 < \mathcal{H}_0(\{z\}) = 1.$$

## Another measure of the size of sets: Hausdorff measure

For  $\beta \geq 0$ , the  $\beta$ -dimensional **Hausdorff measure** of  $A$  is defined by

$$\mathcal{H}_\beta(A) = \lim_{\epsilon \rightarrow 0^+} \inf \left\{ \sum_{i=1}^{\infty} (2r_i)^\beta : A \subseteq \bigcup_{i=1}^{\infty} B(x_i, r_i), \sup_{i \geq 1} r_i \leq \epsilon \right\}.$$

When  $\beta < 0$ , we define  $\mathcal{H}_\beta(A)$  to be infinite.

**Note.** For  $\beta_1 > \beta_2 > 0$ ,

$$\text{Cap}_{\beta_1}(A) > 0 \Rightarrow \mathcal{H}_{\beta_1}(A) > 0 \Rightarrow \text{Cap}_{\beta_2}(A) > 0.$$

**Example.**  $A = \{z\}$

$$\mathcal{H}_\beta(\{z\}) = \begin{cases} \infty & \text{if } \beta < 0 \\ 1 & \text{if } \beta = 0 \\ 0 & \text{if } \beta > 0. \end{cases}$$

**Remark.** For  $\beta = 0$ ,

$$\text{Cap}_0(\{z\}) = 0 < \mathcal{H}_0(\{z\}) = 1.$$

## Another measure of the size of sets: Hausdorff measure

For  $\beta \geq 0$ , the  $\beta$ -dimensional **Hausdorff measure** of  $A$  is defined by

$$\mathcal{H}_\beta(A) = \lim_{\epsilon \rightarrow 0^+} \inf \left\{ \sum_{i=1}^{\infty} (2r_i)^\beta : A \subseteq \bigcup_{i=1}^{\infty} B(x_i, r_i), \sup_{i \geq 1} r_i \leq \epsilon \right\}.$$

When  $\beta < 0$ , we define  $\mathcal{H}_\beta(A)$  to be infinite.

**Note.** For  $\beta_1 > \beta_2 > 0$ ,

$$\text{Cap}_{\beta_1}(A) > 0 \Rightarrow \mathcal{H}_{\beta_1}(A) > 0 \Rightarrow \text{Cap}_{\beta_2}(A) > 0.$$

**Example.**  $A = \{z\}$

$$\mathcal{H}_\beta(\{z\}) = \begin{cases} \infty & \text{if } \beta < 0 \\ 1 & \text{if } \beta = 0 \\ 0 & \text{if } \beta > 0. \end{cases}$$

**Remark.** For  $\beta = 0$ ,

$$\text{Cap}_0(\{z\}) = 0 < \mathcal{H}_0(\{z\}) = 1.$$



## Anisotropic Gaussian fields (Xiao, 2008)

Let  $(V(x), x \in \mathbb{R}^k)$  be a centered continuous Gaussian random field with values in  $\mathbb{R}^d$  with i.i.d. components:  $V(x) = (V_1(x), \dots, V_d(x))$ . Set

$$\sigma^2(x, y) = E[(V_1(x) - V_1(y))^2].$$

Let  $I$  be a “rectangle”. Assume the two conditions:

(C1) There exists  $0 < c < \infty$  and  $H_1, \dots, H_k \in ]0, 1[$  such that for all  $x \in I$ ,

$$c^{-1} \leq \sigma^2(0, x) \leq c,$$

and for all  $x, y \in I$ ,

$$c^{-1} \sum_{j=1}^k |x_j - y_j|^{2H_j} \leq \sigma^2(x, y) \leq c \sum_{j=1}^k |x_j - y_j|^{2H_j}$$

( $H_j$  is the Hölder exponent for coordinate  $j$ ).

(C2) There is  $c > 0$  such that for all  $x, y \in I$ ,

$$\text{Var}(V_1(y) \mid V_1(x)) \geq c \sum_{j=1}^k |x_j - y_j|^{2H_j}.$$

## Anisotropic Gaussian fields (Xiao, 2008)

Let  $(V(x), x \in \mathbb{R}^k)$  be a centered continuous Gaussian random field with values in  $\mathbb{R}^d$  with i.i.d. components:  $V(x) = (V_1(x), \dots, V_d(x))$ . Set

$$\sigma^2(x, y) = E[(V_1(x) - V_1(y))^2].$$

Let  $I$  be a "rectangle". Assume the two conditions:

(C1) There exists  $0 < c < \infty$  and  $H_1, \dots, H_k \in ]0, 1[$  such that for all  $x \in I$ ,

$$c^{-1} \leq \sigma^2(0, x) \leq c,$$

and for all  $x, y \in I$ ,

$$c^{-1} \sum_{j=1}^k |x_j - y_j|^{2H_j} \leq \sigma^2(x, y) \leq c \sum_{j=1}^k |x_j - y_j|^{2H_j}$$

( $H_j$  is the Hölder exponent for coordinate  $j$ ).

(C2) There is  $c > 0$  such that for all  $x, y \in I$ ,

$$\text{Var}(V_1(y) \mid V_1(x)) \geq c \sum_{j=1}^k |x_j - y_j|^{2H_j}.$$

## Anisotropic Gaussian fields (Xiao, 2008)

Let  $(V(x), x \in \mathbb{R}^k)$  be a centered continuous Gaussian random field with values in  $\mathbb{R}^d$  with i.i.d. components:  $V(x) = (V_1(x), \dots, V_d(x))$ . Set

$$\sigma^2(x, y) = E[(V_1(x) - V_1(y))^2].$$

Let  $I$  be a “rectangle”. Assume the two conditions:

(C1) There exists  $0 < c < \infty$  and  $H_1, \dots, H_k \in ]0, 1[$  such that for all  $x \in I$ ,

$$c^{-1} \leq \sigma^2(0, x) \leq c,$$

and for all  $x, y \in I$ ,

$$c^{-1} \sum_{j=1}^k |x_j - y_j|^{2H_j} \leq \sigma^2(x, y) \leq c \sum_{j=1}^k |x_j - y_j|^{2H_j}$$

( $H_j$  is the Hölder exponent for coordinate  $j$ ).

(C2) There is  $c > 0$  such that for all  $x, y \in I$ ,

$$\text{Var}(V_1(y) \mid V_1(x)) \geq c \sum_{j=1}^k |x_j - y_j|^{2H_j}.$$

## Anisotropic Gaussian fields

## Theorem 2 (Biermé, Lacaux &amp; Xiao, 2007)

Fix  $M > 0$ . Set

$$Q = \sum_{j=1}^k \frac{1}{H_j}.$$

Assume  $d > Q$ . Then there is  $0 < C < \infty$  such that for every compact set  $A \subset B(0, M)$ ,

$$C^{-1} \text{Cap}_{d-Q}(A) \leq P\{V(I) \cap A \neq \emptyset\} \leq C \mathcal{H}_{d-Q}(A).$$

Special case obtained by D., Khoshnevisan and E. Nualart (2007)

This results tells us what sort of inequality to aim for when we have a non-Gaussian process and information about its Hölder exponents.

Notice the Hausdorff measure appearing on the right-hand side.

## Anisotropic Gaussian fields

## Theorem 2 (Biermé, Lacaux &amp; Xiao, 2007)

Fix  $M > 0$ . Set

$$Q = \sum_{j=1}^k \frac{1}{H_j}.$$

Assume  $d > Q$ . Then there is  $0 < C < \infty$  such that for every compact set  $A \subset B(0, M)$ ,

$$C^{-1} \text{Cap}_{d-Q}(A) \leq P\{V(I) \cap A \neq \emptyset\} \leq C \mathcal{H}_{d-Q}(A).$$

Special case obtained by D., Khoshnevisan and E. Nualart (2007)

This results tells us what sort of inequality to aim for when we have a non-Gaussian process and information about its Hölder exponents.

Notice the Hausdorff measure appearing on the right-hand side.

## Anisotropic Gaussian fields

## Theorem 2 (Biermé, Lacaux &amp; Xiao, 2007)

Fix  $M > 0$ . Set

$$Q = \sum_{j=1}^k \frac{1}{H_j}.$$

Assume  $d > Q$ . Then there is  $0 < C < \infty$  such that for every compact set  $A \subset B(0, M)$ ,

$$C^{-1} \text{Cap}_{d-Q}(A) \leq P\{V(I) \cap A \neq \emptyset\} \leq C \mathcal{H}_{d-Q}(A).$$

Special case obtained by D., Khoshnevisan and E. Nualart (2007)

This results tells us what sort of inequality to aim for when we have a non-Gaussian process and information about its Hölder exponents.

Notice the Hausdorff measure appearing on the right-hand side.

## Hitting points in the critical dimension

For the **Brownian sheet**  $W$ :

$$P\{W(I) \cap A \neq \emptyset\} \leq C \text{Cap}_{d-2k}(A).$$

If  $d = 2k$  and  $A = \{z\}$  ( $z \in \mathbb{R}^d$ ), then  $\text{Cap}_0(A) = 0$ , so

$$P\{W(I) \cap A \neq \emptyset\} = 0$$

and therefore, **points are polar**.

For an **anisotropic Gaussian random field**  $V$ :

$$P\{V(I) \cap A \neq \emptyset\} \leq C \mathcal{H}_{d-Q}(A).$$

If  $d = Q$  and  $A = \{z\}$  ( $z \in \mathbb{R}^d$ ), then  $\mathcal{H}_0(A) = 1$ , so polarity of points **remains unclear**.

(This issue can be decided on a case-by-case basis for many Gaussian processes.)

## Hitting points in the critical dimension

For the **Brownian sheet**  $W$ :

$$P\{W(I) \cap A \neq \emptyset\} \leq C \text{Cap}_{d-2k}(A).$$

If  $d = 2k$  and  $A = \{z\}$  ( $z \in \mathbb{R}^d$ ), then  $\text{Cap}_0(A) = 0$ , so

$$P\{W(I) \cap A \neq \emptyset\} = 0$$

and therefore, **points are polar**.

For an **anisotropic Gaussian random field**  $V$ :

$$P\{V(I) \cap A \neq \emptyset\} \leq C \mathcal{H}_{d-Q}(A).$$

If  $d = Q$  and  $A = \{z\}$  ( $z \in \mathbb{R}^d$ ), then  $\mathcal{H}_0(A) = 1$ , so polarity of points **remains unclear**.

(This issue can be decided on a case-by-case basis for many Gaussian processes.)



Polarity of points in dimensions  $>$  the critical dimension

Case  $k = 1$ ,  $d \geq 3$ : let  $(B(t), t \in \mathbb{R}_+)$  be a standard Brownian motion with values in  $\mathbb{R}^3$ . Want to explain why it does **not** hit points.

**Explanation.** Let  $t_k = 1 + k2^{-2n}$ . Fix  $x \in \mathbb{R}^d$ . Then

$$\begin{aligned}
 P\{\exists t \in [1, 2] : B(t) = x\} &= P\left(\bigcup_{k=1}^{2^{2n}} \{\exists t \in [t_{k-1}, t_k] : B(t) = x\}\right) \\
 &\leq \sum_{k=1}^{2^{2n}} P\{\exists t \in [t_{k-1}, t_k] : B(t) = x\} \\
 &= \sum_{k=1}^{2^{2n}} [P\{\|B_{t_k} - x\| \leq n2^{-n}\} + e(n)] \\
 &\leq \sum_{k=1}^{2^{2n}} [c(n2^{-n})^d + e(n)] \\
 &= 2^{2n} [c(n2^{-n})^d + e(n)] \\
 &= cn^d 2^{(2-d)n} + 2^{2n} e(n) \\
 &\rightarrow 0 \qquad \text{as } n \rightarrow +\infty \text{ (because } d \geq 3).
 \end{aligned}$$

Polarity of points in dimensions  $>$  the critical dimension

Case  $k = 1$ ,  $d \geq 3$ : let  $(B(t), t \in \mathbb{R}_+)$  be a standard Brownian motion with values in  $\mathbb{R}^3$ . Want to explain why it does **not** hit points.

**Explanation.** Let  $t_k = 1 + k2^{-2n}$ . Fix  $x \in \mathbb{R}^d$ . Then

$$\begin{aligned}
 P\{\exists t \in [1, 2] : B(t) = x\} &= P\left(\bigcup_{k=1}^{2^{2n}} \{\exists t \in [t_{k-1}, t_k] : B(t) = x\}\right) \\
 &\leq \sum_{k=1}^{2^{2n}} P\{\exists t \in [t_{k-1}, t_k] : B(t) = x\} \\
 &= \sum_{k=1}^{2^{2n}} [P\{\|B_{t_k} - x\| \leq n2^{-n}\} + e(n)] \\
 &\leq \sum_{k=1}^{2^{2n}} [c(n2^{-n})^d + e(n)] \\
 &= 2^{2n} [c(n2^{-n})^d + e(n)] \\
 &= cn^d 2^{(2-d)n} + 2^{2n} e(n) \\
 &\rightarrow 0 \qquad \text{as } n \rightarrow +\infty \text{ (because } d \geq 3).
 \end{aligned}$$

## Hitting probabilities for non-Gaussian processes: upper bounds

Let  $U = \{U(t, x), (t, x) \in \mathbb{R}_+ \times \mathbb{R}^k\}$  be an  $\mathbb{R}^d$ -valued continuous process.

## Theorem 3 (D. &amp; Sanz-Solé: upper bound)

Let  $D \subset \mathbb{R}^d$ . Assume that:

(1) For any  $x \in \mathbb{R}^k$ ,  $U(t, x)$  has a *density*  $p_{(t,x)}$ , and

$$\sup_{z \in D^{(2)}} \sup_{(t,x) \in (I \times J)^{(1)}} p_{(t,x)}(z) \leq C$$

$(D^{(2)})$  is the 2-enlargement of  $D$ .

(2) There exist  $\delta_1, \delta_2 \in ]0, 1]$  and a constant  $C$  such that, for any  $q \in [1, \infty[$ ,  $(t, x), (s, y) \in (I \times J)^{(1)}$ ,

$$E(\|U(t, x) - U(s, y)\|^q) \leq C(|t - s|^{\delta_1} + \|x - y\|^{\delta_2})^q.$$

Then for any  $\eta > 0$ , for every Borel set  $A \subset D$ ,

$$P\{\nu(I) \cap A \neq \emptyset\} \leq C \mathcal{H}_{d-\eta-\frac{1}{\delta_1}-\frac{k}{\delta_2}}(A).$$

**Remarks.** (a) Condition (2) is essentially a condition on Hölder continuity.

(b) Condition (1) can often be obtained by using Malliavin calculus.

(c) Note that  $d - \eta$  appears in the upper bound, but this is otherwise similar to the result of Biermé, Lacaux and Xiao (2007).

## Hitting probabilities for non-Gaussian processes: upper bounds

Let  $U = \{U(t, x), (t, x) \in \mathbb{R}_+ \times \mathbb{R}^k\}$  be an  $\mathbb{R}^d$ -valued continuous process.

## Theorem 3 (D. &amp; Sanz-Solé: upper bound)

Let  $D \subset \mathbb{R}^d$ . Assume that:

(1) For any  $x \in \mathbb{R}^k$ ,  $U(t, x)$  has a *density*  $p_{(t,x)}$ , and

$$\sup_{z \in D^{(2)}} \sup_{(t,x) \in (I \times J)^{(1)}} p_{(t,x)}(z) \leq C$$

$(D^{(2)})$  is the 2-enlargement of  $D$ .

(2) There exist  $\delta_1, \delta_2 \in ]0, 1]$  and a constant  $C$  such that, for any  $q \in [1, \infty[$ ,  $(t, x), (s, y) \in (I \times J)^{(1)}$ ,

$$E(\|U(t, x) - U(s, y)\|^q) \leq C(|t - s|^{\delta_1} + \|x - y\|^{\delta_2})^q.$$

Then for any  $\eta > 0$ , for every Borel set  $A \subset D$ ,

$$P\{\nu(I) \cap A \neq \emptyset\} \leq C \mathcal{H}_{d-\eta-\frac{1}{\delta_1}-\frac{k}{\delta_2}}(A).$$

**Remarks.** (a) Condition (2) is essentially a condition on *Hölder continuity*.

(b) Condition (1) can often be obtained by using Malliavin calculus.

(c) Note that  $d - \eta$  appears in the upper bound, but this is otherwise *similar to* the result of Biermé, Lacaux and Xiao (2007).

# Non-polarity of points in dimensions $<$ the critical dimension

Let  $(W(x), x \in \mathbb{R}_+^k)$  be a  $k$ -parameter  $\mathbb{R}^d$ -valued Brownian sheet.

Want to show that for  $d < 2k$ , a point  $z \in \mathbb{R}^d$  is not polar. Set  $I = [1, 2]^k$ .

$$P\{\exists x \in I : W(x) = z\} = \lim_{\varepsilon \downarrow 0} P\{W(I) \cap B(z, \varepsilon) \neq \emptyset\}.$$

Define  $J_\varepsilon = \int_I dx \mathbf{1}_{B(z, \varepsilon)}(W(x))$ . Then

$$P\{W(I) \cap B(z, \varepsilon) \neq \emptyset\} \geq P\{J_\varepsilon > 0\} \geq \frac{(E(J_\varepsilon))^2}{E(J_\varepsilon^2)}.$$

Lower bound on  $E(J_\varepsilon)$ :

$$E(J_\varepsilon) = \int_I dx P\{W(x) \in B(z, \varepsilon)\} \geq \int_I dx \varepsilon^d \inf_{w \in B(z, \varepsilon)} p_x(w) = c \varepsilon^d.$$

Upper bound on  $E(J_\varepsilon^2)$ :

$$\begin{aligned} E(J_\varepsilon^2) &= E \left[ \int_I dx \mathbf{1}_{B(z, \varepsilon)}(W(x)) \int_I dy \mathbf{1}_{B(z, \varepsilon)}(W(y)) \right] \\ &= \int_I dx \int_I dy P\{W(x) \in B(z, \varepsilon), W(y) \in B(z, \varepsilon)\}. \end{aligned}$$

**Need:** (1) a lower bound on the probability density function of  $W(x)$ ;  
(2) an upper bound on the joint probability density function of  $(W(x), W(y))$ .

# Non-polarity of points in dimensions $<$ the critical dimension

Let  $(W(x), x \in \mathbb{R}_+^k)$  be a  $k$ -parameter  $\mathbb{R}^d$ -valued Brownian sheet.

Want to show that for  $d < 2k$ , a point  $z \in \mathbb{R}^d$  is not polar. Set  $I = [1, 2]^k$ .

$$P\{\exists x \in I : W(x) = z\} = \lim_{\varepsilon \downarrow 0} P\{W(I) \cap B(z, \varepsilon) \neq \emptyset\}.$$

Define  $J_\varepsilon = \int_I dx \mathbf{1}_{B(z, \varepsilon)}(W(x))$ . Then

$$P\{W(I) \cap B(z, \varepsilon) \neq \emptyset\} \geq P\{J_\varepsilon > 0\} \geq \frac{E(J_\varepsilon)^2}{E(J_\varepsilon^2)}.$$

Lower bound on  $E(J_\varepsilon)$ :

$$E(J_\varepsilon) = \int_I dx P\{W(x) \in B(z, \varepsilon)\} \geq \int_I dx \varepsilon^d \inf_{w \in B(z, \varepsilon)} p_x(w) = c \varepsilon^d.$$

Upper bound on  $E(J_\varepsilon^2)$ :

$$\begin{aligned} E(J_\varepsilon^2) &= E \left[ \int_I dx \mathbf{1}_{B(z, \varepsilon)}(W(x)) \int_I dy \mathbf{1}_{B(z, \varepsilon)}(W(y)) \right] \\ &= \int_I dx \int_I dy P\{W(x) \in B(z, \varepsilon), W(y) \in B(z, \varepsilon)\}. \end{aligned}$$

**Need:** (1) a lower bound on the probability density function of  $W(x)$ ;  
(2) an upper bound on the joint probability density function of  $(W(x), W(y))$ .

# Non-polarity of points in dimensions $<$ the critical dimension

Let  $(W(x), x \in \mathbb{R}_+^k)$  be a  $k$ -parameter  $\mathbb{R}^d$ -valued Brownian sheet.

Want to show that for  $d < 2k$ , a point  $z \in \mathbb{R}^d$  is not polar. Set  $I = [1, 2]^k$ .

$$P\{\exists x \in I : W(x) = z\} = \lim_{\varepsilon \downarrow 0} P\{W(I) \cap B(z, \varepsilon) \neq \emptyset\}.$$

Define  $J_\varepsilon = \int_I dx \mathbf{1}_{B(z, \varepsilon)}(W(x))$ . Then

$$P\{W(I) \cap B(z, \varepsilon) \neq \emptyset\} \geq P\{J_\varepsilon > 0\} \geq \frac{(E(J_\varepsilon))^2}{E(J_\varepsilon^2)}.$$

Lower bound on  $E(J_\varepsilon)$ :

$$E(J_\varepsilon) = \int_I dx P\{W(x) \in B(z, \varepsilon)\} \geq \int_I dx \varepsilon^d \inf_{w \in B(z, \varepsilon)} p_x(w) = c \varepsilon^d.$$

Upper bound on  $E(J_\varepsilon^2)$ :

$$\begin{aligned} E(J_\varepsilon^2) &= E \left[ \int_I dx \mathbf{1}_{B(z, \varepsilon)}(W(x)) \int_I dy \mathbf{1}_{B(z, \varepsilon)}(W(y)) \right] \\ &= \int_I dx \int_I dy P\{W(x) \in B(z, \varepsilon), W(y) \in B(z, \varepsilon)\}. \end{aligned}$$

**Need:** (1) a **lower** bound on the probability density function of  $W(x)$ ;  
(2) an **upper** bound on the joint probability density function of  $(W(x), W(y))$ .

## Hitting probabilities for non-Gaussian processes: lower bounds

Let  $U = \{U(x), x \in \mathbb{R}^k\}$ ,  $k \in \mathbb{N}^*$ , be an  $\mathbb{R}^d$ -valued continuous process.

## Theorem 4 (D. &amp; Sanz-Solé)

Fix  $N > 0$ ,  $I \subset \mathbb{R}^k$  compact with positive Lebesgue measure, and assume:

(1) The density  $p_x$  of  $U(x)$  is continuous, bounded, and positive.

(2) For any  $x, y \in I$  with  $x \neq y$ ,  $(U(x), U(y))$  has a density  $p_{x,y}$  w.r.t.

Lebesgue measure in  $\mathbb{R}^{2d}$ , and there exist  $\gamma, \alpha \in ]0, \infty[$  such that for any  $z_1, z_2 \in [-N, N]^d$

$$p_{x,y}(z_1, z_2) \leq \frac{C}{\|x - y\|^\gamma} \left[ \frac{\|x - y\|^\alpha}{\|z_1 - z_2\|} \wedge 1 \right]^p,$$

where  $p > (\gamma - k) \frac{2d}{\alpha} \vee 2$ . Then there exists  $c > 0$  such that for all Borel sets  $A \subset [-N, N]^d$ ,

$$P\{U(I) \cap A \neq \emptyset\} \geq c \operatorname{Cap}_{\frac{1}{\alpha}(\gamma-k)}(A).$$

**Remark.** The r.h.s. in (2) is **not** of Gaussian type. It is a weaker condition.



## Non-linear systems of stochastic p.d.e.'s

Let  $L$  be a partial differential operator (e.g.  $L = \frac{\partial}{\partial t} - \Delta$ ).

Let  $u(t, x) = (u^1(t, x), \dots, u^d(t, x)) \in \mathbb{R}^d$  be the solution of

$$\begin{cases} Lu^1(t, x) = b^1(u(t, x)) + \sum_{j=1}^d \sigma_{1,j}(u(t, x)) \dot{W}_j(t, x), \\ \vdots \\ Lu^d(t, x) = b^d(u(t, x)) + \sum_{j=1}^d \sigma_{d,j}(u(t, x)) \dot{W}_j(t, x), \end{cases}$$

$$t \in ]0, T], \quad x \in \mathbb{R}^k.$$

Lipschitz non-linearities:  $b^i, \sigma_{i,j} : \mathbb{R}^d \rightarrow \mathbb{R}, \quad i = 1, \dots, d$

Initial conditions: e.g.  $u(0, x) = u_0(x)$  given.

$\dot{W}_j(t, x)$ : Gaussian noise.

## Non-linear systems of stochastic p.d.e.'s

Let  $L$  be a partial differential operator (e.g.  $L = \frac{\partial}{\partial t} - \Delta$ ).

Let  $u(t, x) = (u^1(t, x), \dots, u^d(t, x)) \in \mathbb{R}^d$  be the solution of

$$\begin{cases} Lu^1(t, x) = b^1(u(t, x)) + \sum_{j=1}^d \sigma_{1,j}(u(t, x)) \dot{W}_j(t, x), \\ \vdots \\ Lu^d(t, x) = b^d(u(t, x)) + \sum_{j=1}^d \sigma_{d,j}(u(t, x)) \dot{W}_j(t, x), \end{cases}$$

$$t \in ]0, T], \quad x \in \mathbb{R}^k.$$

Lipschitz non-linearities:  $b^i, \sigma_{i,j} : \mathbb{R}^d \rightarrow \mathbb{R}, \quad i = 1, \dots, d$

Initial conditions: e.g.  $u(0, x) = u_0(x)$  given.

$\dot{W}_j(t, x)$ : Gaussian noise.

## Non-linear systems of stochastic p.d.e.'s

Let  $L$  be a partial differential operator (e.g.  $L = \frac{\partial}{\partial t} - \Delta$ ).

Let  $u(t, x) = (u^1(t, x), \dots, u^d(t, x)) \in \mathbb{R}^d$  be the solution of

$$\begin{cases} Lu^1(t, x) = b^1(u(t, x)) + \sum_{j=1}^d \sigma_{1,j}(u(t, x)) \dot{W}_j(t, x), \\ \vdots \\ Lu^d(t, x) = b^d(u(t, x)) + \sum_{j=1}^d \sigma_{d,j}(u(t, x)) \dot{W}_j(t, x), \end{cases}$$

$$t \in ]0, T], \quad x \in \mathbb{R}^k.$$

Lipschitz non-linearities:  $b^i, \sigma_{i,j} : \mathbb{R}^d \rightarrow \mathbb{R}, \quad i = 1, \dots, d$

Initial conditions: e.g.  $u(0, x) = u_0(x)$  given.

$\dot{W}_j(t, x)$ : Gaussian noise.

## Cases considered

Wave equation,  $k = 1$  (D. & E. Nualart, 2004):

$$Lu^i(t, x) = \frac{\partial^2 u^i}{\partial t^2}(t, x) - \frac{\partial^2 u^i}{\partial x^2}(t, x)$$

Heat equation,  $k = 1$  (D., Khoshnevisan & E. Nualart, 2007, 2009)

$$Lu^i(t, x) = \frac{\partial u^i}{\partial t}(t, x) - \frac{\partial^2 u^i}{\partial x^2}(t, x)$$

$\dot{W}_j(t, x)$  : space-time white noise

Heat equation,  $k \geq 1$  (D., Khoshnevisan & E. Nualart, 2013)

$$Lu^i(t, x) = \frac{\partial u^i}{\partial t}(t, x) - \Delta u^i(t, x)$$

Wave equation,  $k \in \{1, 2, 3\}$  (D. & Sanz-Solé, Memoirs AMS, 2014?)

$$Lu^i(t, x) = \frac{\partial^2 u^i}{\partial t^2}(t, x) - \Delta u^i(t, x)$$

$\dot{W}_j(t, x)$ : white in time, spatially homogeneous noise (covariance kernel  $\|x - y\|^{-\beta}$ )

## Cases considered

Wave equation,  $k = 1$  (D. & E. Nualart, 2004):

$$Lu^i(t, x) = \frac{\partial^2 u^i}{\partial t^2}(t, x) - \frac{\partial^2 u^i}{\partial x^2}(t, x)$$

Heat equation,  $k = 1$  (D., Khoshnevisan & E. Nualart, 2007, 2009)

$$Lu^i(t, x) = \frac{\partial u^i}{\partial t}(t, x) - \frac{\partial^2 u^i}{\partial x^2}(t, x)$$

$\dot{W}_j(t, x)$  : space-time white noise

Heat equation,  $k \geq 1$  (D., Khoshnevisan & E. Nualart, 2013)

$$Lu^i(t, x) = \frac{\partial u^i}{\partial t}(t, x) - \Delta u^i(t, x)$$

Wave equation,  $k \in \{1, 2, 3\}$  (D. & Sanz-Solé, Memoirs AMS, 2014?)

$$Lu^i(t, x) = \frac{\partial^2 u^i}{\partial t^2}(t, x) - \Delta u^i(t, x)$$

$\dot{W}_j(t, x)$ : white in time, spatially homogeneous noise (covariance kernel  $\|x - y\|^{-\beta}$ )

## Cases considered

Wave equation,  $k = 1$  (D. & E. Nualart, 2004):

$$Lu^i(t, x) = \frac{\partial^2 u^i}{\partial t^2}(t, x) - \frac{\partial^2 u^i}{\partial x^2}(t, x)$$

Heat equation,  $k = 1$  (D., Khoshnevisan & E. Nualart, 2007, 2009)

$$Lu^i(t, x) = \frac{\partial u^i}{\partial t}(t, x) - \frac{\partial^2 u^i}{\partial x^2}(t, x)$$

$\dot{W}_j(t, x)$  : space-time white noise

Heat equation,  $k \geq 1$  (D., Khoshnevisan & E. Nualart, 2013)

$$Lu^i(t, x) = \frac{\partial u^i}{\partial t}(t, x) - \Delta u^i(t, x)$$

Wave equation,  $k \in \{1, 2, 3\}$  (D. & Sanz-Solé, Memoirs AMS, 2014?)

$$Lu^i(t, x) = \frac{\partial^2 u^i}{\partial t^2}(t, x) - \Delta u^i(t, x)$$

$\dot{W}_j(t, x)$ : white in time, spatially homogeneous noise (covariance kernel  $\|x - y\|^{-\beta}$ )

## Cases considered

Wave equation,  $k = 1$  (D. & E. Nualart, 2004):

$$Lu^i(t, x) = \frac{\partial^2 u^i}{\partial t^2}(t, x) - \frac{\partial^2 u^i}{\partial x^2}(t, x)$$

Heat equation,  $k = 1$  (D., Khoshnevisan & E. Nualart, 2007, 2009)

$$Lu^i(t, x) = \frac{\partial u^i}{\partial t}(t, x) - \frac{\partial^2 u^i}{\partial x^2}(t, x)$$

$\dot{W}_j(t, x)$  : space-time white noise

Heat equation,  $k \geq 1$  (D., Khoshnevisan & E. Nualart, 2013)

$$Lu^i(t, x) = \frac{\partial u^i}{\partial t}(t, x) - \Delta u^i(t, x)$$

Wave equation,  $k \in \{1, 2, 3\}$  (D. & Sanz-Solé, Memoirs AMS, 2014?)

$$Lu^i(t, x) = \frac{\partial^2 u^i}{\partial t^2}(t, x) - \Delta u^i(t, x)$$

$\dot{W}_j(t, x)$ : white in time, spatially homogeneous noise (covariance kernel  $\|x - y\|^{-\beta}$ )

# The driving noise

The spatial dimension is  $k \geq 1$  ( $x \in \mathbb{R}^k$ ).

$k = 1$ . Usually,  $\dot{W}(t, x)$  is space-time white noise with values in  $\mathbb{R}^d$ :

$$\dot{W}(t, x) = (\dot{W}_1(t, x), \dots, \dot{W}_d(t, x))$$

with covariance

$$E [\dot{W}_i(t, x) \dot{W}_j(s, y)] = \delta(t - s) \delta(x - y) \delta_{ij}.$$

$k \geq 1$ .  $\dot{W}(t, x)$  is spatially homogeneous Gaussian noise that is white in time:

$$\dot{W}(t, x) = (\dot{W}_1(t, x), \dots, \dot{W}_d(t, x))$$

with covariance of the form

$$E [\dot{W}_i(t, x) \dot{W}_j(s, y)] = \delta(t - s) \|x - y\|^{-\beta} \delta_{ij},$$

where  $0 < \beta < k$  and  $\|\cdot\|$  is the Euclidean norm.



# The driving noise

The spatial dimension is  $k \geq 1$  ( $x \in \mathbb{R}^k$ ).

$k = 1$ . Usually,  $\dot{W}(t, x)$  is space-time white noise with values in  $\mathbb{R}^d$ :

$$\dot{W}(t, x) = (\dot{W}_1(t, x), \dots, \dot{W}_d(t, x))$$

with covariance

$$E [\dot{W}_i(t, x) \dot{W}_j(s, y)] = \delta(t - s) \delta(x - y) \delta_{ij}.$$

$k \geq 1$ .  $\dot{W}(t, x)$  is spatially homogeneous Gaussian noise that is white in time:

$$\dot{W}(t, x) = (\dot{W}_1(t, x), \dots, \dot{W}_d(t, x))$$

with covariance of the form

$$E [\dot{W}_i(t, x) \dot{W}_j(s, y)] = \delta(t - s) \|x - y\|^{-\beta} \delta_{ij},$$

where  $0 < \beta < k$  and  $\|\cdot\|$  is the Euclidean norm.

# Preliminaries to discussing hitting probabilities

## Upper bounds

- Existence (+ uniq.) of a random field solution  $(u(t, x))$ . Walsh (1986), ...  
 Condition  $0 < \beta < (2 \wedge k)$  is necessary and sufficient.
- Moments of increments (Hölder continuity), optimal exponents (!):

$$\|u(s, y) - u(t, x)\|_{L^p} \leq \Delta(s, y; t, x)$$

Typically,

$$\Delta(s, y; t, x) = |t - s|^{H_1} + \|x - y\|^{H_2}$$

Heat equation,  $k=1$ :  $H_1 = \frac{1}{4}$ ,  $H_2 = \frac{1}{2}$ ;       $k \geq 1$ :  $H_1 < \frac{2-\beta}{4}$ ,  $H_2 < \frac{2-\beta}{2}$

Wave equation,  $k=1$ :  $H_1 = H_2 = \frac{1}{2}$ ;       $k \in \{1, 2, 3\}$ :  $H_1 = H_2 < \frac{2-\beta}{2}$   
 (D. & Sanz-Solé, MAMS (2009))

- existence of a uniformly bounded density. Uses additional smoothness and uniform ellipticity hypotheses on  $b$  and  $\sigma$  and Malliavin calculus.

These three properties lead to an **upper bound** on hitting probabilities, in terms of **Hausdorff measure**.

## Preliminaries to discussing hitting probabilities

## Upper bounds

- Existence (+ uniq.) of a random field solution  $(u(t, x))$ . Walsh (1986), ...  
Condition  $0 < \beta < (2 \wedge k)$  is necessary and sufficient.
- Moments of increments (Hölder continuity), optimal exponents (!):

$$\|u(s, y) - u(t, x)\|_{L^p} \leq \Delta(s, y; t, x)$$

Typically,

$$\Delta(s, y; t, x) = |t - s|^{H_1} + \|x - y\|^{H_2}$$

Heat equation,  $k=1$ :  $H_1 = \frac{1}{4}$ ,  $H_2 = \frac{1}{2}$ ;

$k \geq 1$ :  $H_1 < \frac{2-\beta}{4}$ ,  $H_2 < \frac{2-\beta}{2}$

Wave equation,  $k=1$ :  $H_1 = H_2 = \frac{1}{2}$ ;

$k \in \{1, 2, 3\}$ :  $H_1 = H_2 < \frac{2-\beta}{2}$

(D. & Sanz-Solé, MAMS (2009))

- existence of a uniformly bounded density. Uses additional smoothness and uniform ellipticity hypotheses on  $b$  and  $\sigma$  and Malliavin calculus.

These three properties lead to an upper bound on hitting probabilities, in terms of Hausdorff measure.

# Preliminaries to discussing hitting probabilities

## Upper bounds

- Existence (+ uniq.) of a random field solution  $(u(t, x))$ . Walsh (1986), ...  
 Condition  $0 < \beta < (2 \wedge k)$  is necessary and sufficient.
- Moments of increments (Hölder continuity), optimal exponents (!):

$$\|u(s, y) - u(t, x)\|_{L^p} \leq \Delta(s, y; t, x)$$

Typically,

$$\Delta(s, y; t, x) = |t - s|^{H_1} + \|x - y\|^{H_2}$$

Heat equation,  $k=1$ :  $H_1 = \frac{1}{4}$ ,  $H_2 = \frac{1}{2}$ ;       $k \geq 1$ :  $H_1 < \frac{2-\beta}{4}$ ,  $H_2 < \frac{2-\beta}{2}$

Wave equation,  $k=1$ :  $H_1 = H_2 = \frac{1}{2}$ ;       $k \in \{1, 2, 3\}$ :  $H_1 = H_2 < \frac{2-\beta}{2}$   
 (D. & Sanz-Solé, MAMS (2009))

- existence of a uniformly bounded density. Uses additional smoothness and uniform ellipticity hypotheses on  $b$  and  $\sigma$  and [Malliavin calculus](#).

These three properties lead to an [upper bound](#) on hitting probabilities, in terms of [Hausdorff measure](#).

## Preliminaries to discussing hitting probabilities

## Upper bounds

- Existence (+ uniq.) of a random field solution  $(u(t, x))$ . Walsh (1986), ...  
Condition  $0 < \beta < (2 \wedge k)$  is necessary and sufficient.
- Moments of increments (Hölder continuity), optimal exponents (!):

$$\|u(s, y) - u(t, x)\|_{L^p} \leq \Delta(s, y; t, x)$$

Typically,

$$\Delta(s, y; t, x) = |t - s|^{H_1} + \|x - y\|^{H_2}$$

Heat equation,  $k=1$ :  $H_1 = \frac{1}{4}$ ,  $H_2 = \frac{1}{2}$ ;       $k \geq 1$ :  $H_1 < \frac{2-\beta}{4}$ ,  $H_2 < \frac{2-\beta}{2}$

Wave equation,  $k=1$ :  $H_1 = H_2 = \frac{1}{2}$ ;       $k \in \{1, 2, 3\}$ :  $H_1 = H_2 < \frac{2-\beta}{2}$   
(D. & Sanz-Solé, MAMS (2009))

- existence of a uniformly bounded density. Uses additional smoothness and uniform ellipticity hypotheses on  $b$  and  $\sigma$  and Malliavin calculus.

These three properties lead to an **upper bound** on hitting probabilities, in terms of **Hausdorff measure**.

## Upper bounds on hitting probabilities

moments of increments + uniformly bounded density

lead to the following upper bound on hitting probabilities:

$$P\{u(I \times J) \cap A \neq \emptyset\} \leq c_\eta \mathcal{H}_{d-Q-\eta}(A) \quad (\eta > 0)$$

where  $Q = \frac{1}{H_1} + \frac{k}{H_2}$ .

Corollary (Polarity of points)

*For the systems of stochastic heat and wave equations, points are polar if  $d > Q$ .*

## Upper bounds on hitting probabilities

moments of increments + uniformly bounded density

lead to the following upper bound on hitting probabilities:

$$P\{u(I \times J) \cap A \neq \emptyset\} \leq c_\eta \mathcal{H}_{d-Q-\eta}(A) \quad (\eta > 0)$$

where  $Q = \frac{1}{H_1} + \frac{k}{H_2}$ .

### Corollary (Polarity of points)

*For the systems of stochastic heat and wave equations, points are polar if  $d > Q$ .*

# Preliminaries to discussing hitting probabilities

## Lower bounds

- Positivity of the density of  $u(t, x)$  [available in the literature]
- Upper bound on the density of  $(u(s, y), u(t, x))$  (two-point density):

$$p_{s,y;t,x}(z_1, z_2) \leq [\Delta(s, y; t, x)]^{-\gamma} \left[ \frac{(\Delta(s, y; t, x))^2}{\|z_1 - z_2\|^2} \wedge 1 \right]^{p/2d}$$

Typically,  $\gamma$  depends on  $d$ , and the best result would be with  $\gamma = d$  (true for Gaussian case  $b \equiv 0$ ,  $\sigma \equiv \text{Id}$ ).

These two properties (obtained via [Malliavin calculus](#)) lead to a [lower bound](#) on hitting probabilities:

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c \text{Cap}_{\gamma-Q}(A).$$

where  $Q = \frac{1}{H_1} + \frac{k}{H_2}$ . (optimal if  $\gamma = d$ )

Corollary (Non-polarity of points)

*For the systems of stochastic heat and wave equations, points are not polar if  $\gamma < Q$ .*



# Preliminaries to discussing hitting probabilities

## Lower bounds

- Positivity of the density of  $u(t, x)$  [available in the literature]
- Upper bound on the density of  $(u(s, y), u(t, x))$  (two-point density):

$$p_{s,y;t,x}(z_1, z_2) \leq [\Delta(s, y; t, x)]^{-\gamma} \left[ \frac{(\Delta(s, y; t, x))^2}{\|z_1 - z_2\|^2} \wedge 1 \right]^{p/2d}$$

Typically,  $\gamma$  depends on  $d$ , and the best result would be with  $\gamma = d$  (true for Gaussian case  $b \equiv 0$ ,  $\sigma \equiv Id$ ).

These two properties (obtained via Malliavin calculus) lead to a lower bound on hitting probabilities:

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c \text{Cap}_{\gamma-Q}(A).$$

where  $Q = \frac{1}{H_1} + \frac{k}{H_2}$ . (optimal if  $\gamma = d$ )

Corollary (Non-polarity of points)

*For the systems of stochastic heat and wave equations, points are not polar if  $\gamma < Q$ .*

# Preliminaries to discussing hitting probabilities

## Lower bounds

- Positivity of the density of  $u(t, x)$  [available in the literature]
- Upper bound on the density of  $(u(s, y), u(t, x))$  (two-point density):

$$p_{s,y;t,x}(z_1, z_2) \leq [\Delta(s, y; t, x)]^{-\gamma} \left[ \frac{(\Delta(s, y; t, x))^2}{\|z_1 - z_2\|^2} \wedge 1 \right]^{p/2d}$$

Typically,  $\gamma$  depends on  $d$ , and the best result would be with  $\gamma = d$  (true for Gaussian case  $b \equiv 0$ ,  $\sigma \equiv \text{Id}$ ).

These two properties (obtained via [Malliavin calculus](#)) lead to a **lower bound** on hitting probabilities:

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c \text{Cap}_{\gamma-Q}(A).$$

where  $Q = \frac{1}{H_1} + \frac{k}{H_2}$ . (optimal if  $\gamma = d$ )

### Corollary (Non-polarity of points)

*For the systems of stochastic heat and wave equations, points are not polar if  $\gamma < Q$ .*

## Results for systems of non-linear equations

Wave equation,  $k = 1$ , space-time white noise (D. & E. Nualart, 2004):

$$\gamma = d, H_1 = H_2 = \frac{1}{2},$$

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c \operatorname{Cap}_{d-4}(A)$$

Heat equation,  $k = 1$ , space-time white noise (D., Khoshnevisan & E. Nualart, 2007, 2009)

$$\gamma = d + \eta \ (\eta > 0), H_1 = \frac{1}{4}, H_2 = \frac{1}{2},$$

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c_\eta \operatorname{Cap}_{d+\eta-6}(A)$$

Heat equation,  $k \geq 1$ , homog. noise  $\beta$  (D., Khoshnevisan & E. Nualart, 2013)

$$\gamma = d + \eta \ (\eta > 0), H_1 = \frac{2-\beta}{4}, H_2 = \frac{2-\beta}{2},$$

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c_\eta \operatorname{Cap}_{d+\eta-\frac{4+2k}{2-\beta}}(A)$$

Wave equation,  $k \in \{1, 2, 3\}$ , homog. noise  $\beta$  (D., Sanz-Solé, MAMS, 2014?)

$$\gamma = d + \frac{4d^2}{2-\beta} + \eta \ (\eta > 0), H_1 = H_2 = \frac{2-\beta}{2},$$

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c_\eta \operatorname{Cap}_{d+\frac{4d^2}{2-\beta}+\eta-\frac{2+2k}{2-\beta}}(A)$$

## Results for systems of non-linear equations

Wave equation,  $k = 1$ , space-time white noise (D. & E. Nualart, 2004):

$$\gamma = d, H_1 = H_2 = \frac{1}{2},$$

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c \operatorname{Cap}_{d-4}(A)$$

Heat equation,  $k = 1$ , space-time white noise (D., Khoshnevisan & E. Nualart, 2007, 2009)

$$\gamma = d + \eta \ (\eta > 0), H_1 = \frac{1}{4}, H_2 = \frac{1}{2},$$

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c_\eta \operatorname{Cap}_{d+\eta-6}(A)$$

Heat equation,  $k \geq 1$ , homog. noise  $\beta$  (D., Khoshnevisan & E. Nualart, 2013)

$$\gamma = d + \eta \ (\eta > 0), H_1 = \frac{2-\beta}{4}, H_2 = \frac{2-\beta}{2},$$

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c_\eta \operatorname{Cap}_{d+\eta-\frac{4+2k}{2-\beta}}(A)$$

Wave equation,  $k \in \{1, 2, 3\}$ , homog. noise  $\beta$  (D., Sanz-Solé, MAMS, 2014?)

$$\gamma = d + \frac{4d^2}{2-\beta} + \eta \ (\eta > 0), H_1 = H_2 = \frac{2-\beta}{2},$$

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c_\eta \operatorname{Cap}_{d+\frac{4d^2}{2-\beta}+\eta-\frac{2+2k}{2-\beta}}(A)$$

## Results for systems of non-linear equations

Wave equation,  $k = 1$ , space-time white noise (D. & E. Nualart, 2004):

$$\gamma = d, H_1 = H_2 = \frac{1}{2},$$

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c \operatorname{Cap}_{d-4}(A)$$

Heat equation,  $k = 1$ , space-time white noise (D., Khoshnevisan & E. Nualart, 2007, 2009)

$$\gamma = d + \eta \ (\eta > 0), H_1 = \frac{1}{4}, H_2 = \frac{1}{2},$$

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c_\eta \operatorname{Cap}_{d+\eta-6}(A)$$

Heat equation,  $k \geq 1$ , homog. noise  $\beta$  (D., Khoshnevisan & E. Nualart, 2013)

$$\gamma = d + \eta \ (\eta > 0), H_1 = \frac{2-\beta}{4}, H_2 = \frac{2-\beta}{2},$$

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c_\eta \operatorname{Cap}_{d+\eta-\frac{4+2k}{2-\beta}}(A)$$

Wave equation,  $k \in \{1, 2, 3\}$ , homog. noise  $\beta$  (D., Sanz-Solé, MAMS, 2014?)

$$\gamma = d + \frac{4d^2}{2-\beta} + \eta \ (\eta > 0), H_1 = H_2 = \frac{2-\beta}{2},$$

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c_\eta \operatorname{Cap}_{d+\frac{4d^2}{2-\beta}+\eta-\frac{2+2k}{2-\beta}}(A)$$

## Results for systems of non-linear equations

Wave equation,  $k = 1$ , space-time white noise (D. & E. Nualart, 2004):

$$\gamma = d, H_1 = H_2 = \frac{1}{2},$$

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c \operatorname{Cap}_{d-4}(A)$$

Heat equation,  $k = 1$ , space-time white noise (D., Khoshnevisan & E. Nualart, 2007, 2009)

$$\gamma = d + \eta \ (\eta > 0), H_1 = \frac{1}{4}, H_2 = \frac{1}{2},$$

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c_\eta \operatorname{Cap}_{d+\eta-6}(A)$$

Heat equation,  $k \geq 1$ , homog. noise  $\beta$  (D., Khoshnevisan & E. Nualart, 2013)

$$\gamma = d + \eta \ (\eta > 0), H_1 = \frac{2-\beta}{4}, H_2 = \frac{2-\beta}{2},$$

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c_\eta \operatorname{Cap}_{d+\eta-\frac{4+2k}{2-\beta}}(A)$$

Wave equation,  $k \in \{1, 2, 3\}$ , homog. noise  $\beta$  (D., Sanz-Solé, MAMS, 2014?)

$$\gamma = d + \frac{4d^2}{2-\beta} + \eta \ (\eta > 0), H_1 = H_2 = \frac{2-\beta}{2},$$

$$P\{u(I \times J) \cap A \neq \emptyset\} \geq c_\eta \operatorname{Cap}_{d+\frac{4d^2}{2-\beta}+\eta-\frac{2+2k}{2-\beta}}(A)$$

# What about the critical dimension?

The previous results state that points are polar if  $d > Q$ , and are not polar if  $d < Q$ , where  $Q = \frac{1}{H_1} + \frac{k}{H_2}$ . What if  $Q$  is an integer and  $d = Q$ ?

Even in the Gaussian case, there is no general theory (but the answer is known in various cases).

Mueller & Tribe (2002). Linear stochastic heat equation:

$$\frac{\partial u^i}{\partial t}(t, x) - \frac{\partial^2 u^i}{\partial x^2}(t, x) = \sigma \dot{W}^i(t, x), \quad t > 0, x \in \mathbb{R},$$

but only in the case  $\sigma \equiv 1$ : the method does not apply to a deterministic function  $\sigma = \sigma(t, x)$ !

A method of Talagrand (1995, 1998). Based a harmonic representation (of fractional Brownian motion).

Ongoing project with C. Mueller & Y. Xiao.

# What about the critical dimension?

The previous results state that points are polar if  $d > Q$ , and are not polar if  $d < Q$ , where  $Q = \frac{1}{H_1} + \frac{k}{H_2}$ . What if  $Q$  is an integer and  $d = Q$ ?

Even in the Gaussian case, there is no general theory (but the answer is known in various cases).

Mueller & Tribe (2002). Linear stochastic heat equation:

$$\frac{\partial u^i}{\partial t}(t, x) - \frac{\partial^2 u^i}{\partial x^2}(t, x) = \sigma \dot{W}^i(t, x), \quad t > 0, x \in \mathbb{R},$$

but only in the case  $\sigma \equiv 1$ : the method does not apply to a deterministic function  $\sigma = \sigma(t, x)$ !

A method of Talagrand (1995, 1998). Based a harmonic representation (of fractional Brownian motion).

Ongoing project with C. Mueller & Y. Xiao.



# What about the critical dimension?

The previous results state that points are polar if  $d > Q$ , and are not polar if  $d < Q$ , where  $Q = \frac{1}{H_1} + \frac{k}{H_2}$ . What if  $Q$  is an integer and  $d = Q$ ?

Even in the Gaussian case, there is no general theory (but the answer is known in various cases).

Mueller & Tribe (2002). Linear stochastic heat equation:

$$\frac{\partial u^i}{\partial t}(t, x) - \frac{\partial^2 u^i}{\partial x^2}(t, x) = \sigma \dot{W}^i(t, x), \quad t > 0, x \in \mathbb{R},$$

but only in the case  $\sigma \equiv 1$ : the method does not apply to a deterministic function  $\sigma = \sigma(t, x)$ !

A method of Talagrand (1995, 1998). Based a harmonic representation (of fractional Brownian motion).

Ongoing project with C. Mueller & Y. Xiao.

# A harmonic representation of the solution to the linear stochastic heat equation in spatial dimension 1

Let  $W_1(d\tau, d\xi)$  and  $W_2(d\tau, d\xi)$  be two independent real-valued space-time white noises. Set

$$\begin{aligned}
 v(t, x) = & \int_{\mathbb{R}} \int_{\mathbb{R}} (\xi^4 + \tau^2)^{-1} [\cos(\xi x)(\cos(\tau t) - e^{-t\xi^2}) - \sin(\xi x) \sin(\tau t)] \\
 & \times (\xi^2 W_1(d\tau, d\xi) - \tau W_2(d\tau, d\xi)) \\
 & + \int_{\mathbb{R}} \int_{\mathbb{R}} (\xi^4 + \tau^2)^{-1} [\sin(\xi x)(\cos(\tau t) - e^{-t\xi^2}) - \cos(\xi x) \sin(\tau t)] \\
 & \times (\xi^2 W_2(d\tau, d\xi) - \tau W_1(d\tau, d\xi))
 \end{aligned} \tag{1}$$

## Observations.

- (1)  $v(0, x) = 0$  and  $\frac{\partial v}{\partial t} - \frac{\partial^2 v}{\partial x^2}$  is a space-time white noise.
- (2) Such formulas can be obtained for many linear spde's, and then Talagrand's method can be applied.
- (3) Solution to non-linear spde's can be (locally) approximated by (conditionally) linear spde's, so we expect to handle the critical dimensions for many non-linear systems of spde's.

# A harmonic representation of the solution to the linear stochastic heat equation in spatial dimension 1

Let  $W_1(d\tau, d\xi)$  and  $W_2(d\tau, d\xi)$  be two independent real-valued space-time white noises. Set

$$\begin{aligned}
 v(t, x) = & \int_{\mathbb{R}} \int_{\mathbb{R}} (\xi^4 + \tau^2)^{-1} [\cos(\xi x)(\cos(\tau t) - e^{-t\xi^2}) - \sin(\xi x) \sin(\tau t)] \\
 & \times (\xi^2 W_1(d\tau, d\xi) - \tau W_2(d\tau, d\xi)) \\
 & + \int_{\mathbb{R}} \int_{\mathbb{R}} (\xi^4 + \tau^2)^{-1} [\sin(\xi x)(\cos(\tau t) - e^{-t\xi^2}) - \cos(\xi x) \sin(\tau t)] \\
 & \times (\xi^2 W_2(d\tau, d\xi) - \tau W_1(d\tau, d\xi))
 \end{aligned} \tag{1}$$

## Observations.

- (1)  $v(0, x) = 0$  and  $\frac{\partial v}{\partial t} - \frac{\partial^2 v}{\partial x^2}$  is a space-time white noise.
- (2) Such formulas can be obtained for many linear spde's, and then Talagrand's method can be applied.
- (3) Solution to non-linear spde's can be (locally) approximated by (conditionally) linear spde's, so we expect to handle the critical dimensions for many non-linear systems of spde's.

## Publications on hitting probabilities

Dalang, R.C. and Nualart, E. Potential theory for **hyperbolic** spde's. *Annals Probab.* **32** (2004), 2099-2148.

Dalang, R.C., Khoshnevisan, D. and Nualart, E., Hitting probabilities for systems of non-linear stochastic **heat** equations with **additive** noise. *ALEA* **3** (2007), 231-271.

Dalang, R.C., Khoshnevisan, D. and Nualart, E., Hitting probabilities for systems of non-linear stochastic **heat** equations with **multiplicative** noise. *Probab. Th. Rel. Fields* **144** (2009), 371-427.

Dalang, R.C. and Sanz-Solé, Criteria for hitting probabilities with applications to systems of stochastic **wave** equations. *The Bernoulli Journal* **16-4** (2010), 1343-1368.

Dalang, R.C., Khoshnevisan, D. and Nualart, E., Hitting probabilities for systems of non-linear stochastic **heat** equations in **spatial dimension  $k \geq 1$** . *Journal of SPDE's: Analysis and Computations* **1-1** (2013), 94-151.

Dalang, R.C. and Sanz-Solé, Hitting probabilities for non-linear systems of stochastic **waves**. *Memoirs of the American Math. Soc.* (2014, to appear).